

TERRA)UE

Advancing Earth Science

Using SNAP in Cloud processing services for GEP

Φ-week event

10 September 2019

ESA-ESRIN



- Terradue is an European Space Agency spin-off started in 2006
 - Based in Rome, staff of 16 from 6 nationalities
- Providing support to application builders in Earth sciences
 - To use satellite EO data as information source
 - Cloud PaaS, complemented with APIs for Cloud bursting
- Business model: Platform-centered, a collaborative workplace “**Ellip**” for value adders to interact & co-create

- R&D activities to create an ecosystem of interconnected Thematic Exploitation Platforms
- Users access a work environment containing the data and resources required, as opposed to downloading and replicating the data "at home"

The fundamental principle is to move the User to the data and tools

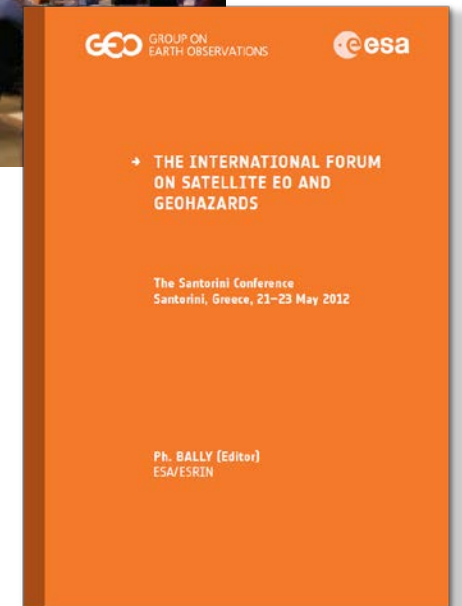


GEP designed in the context of:

- Geohazards Supersite initiative (GSNL)
- CEOS Disasters Working Group

User-driven model for partnership and community building

Started from Int. Forum on Satellite EO and Geohazards organised by ESA and GEO in Santorini in 2012 (140+ participants)



Platform based on virtualization & federation of EO data

- Provide services & support to the geohazards community

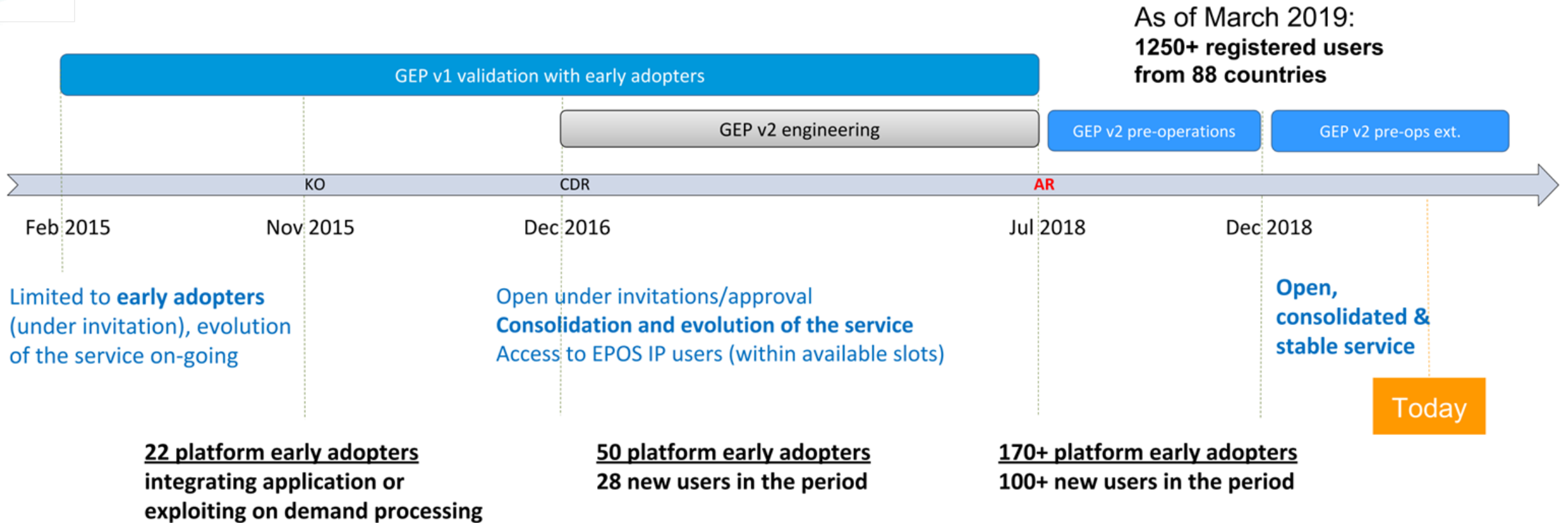
On-demand & systematic processing services

- Cloud Compute power, managing multi-tenant resources

Access to Copernicus Sentinels repositories

- Plus access to hundred TBs of EO data archives (ERS and ENVISAT), and other EO missions (ALOS-2, Cosmo-SkyMed and TerraSAR-X) under CEOS WG Disaster and the GSNL agreements

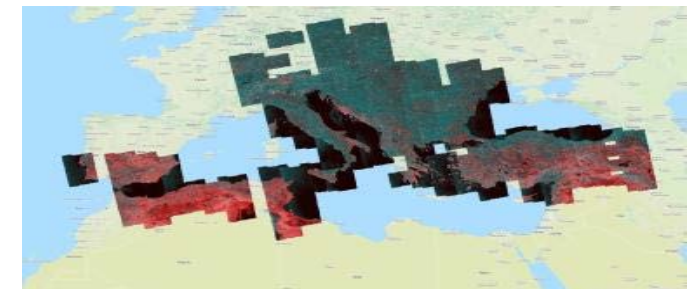
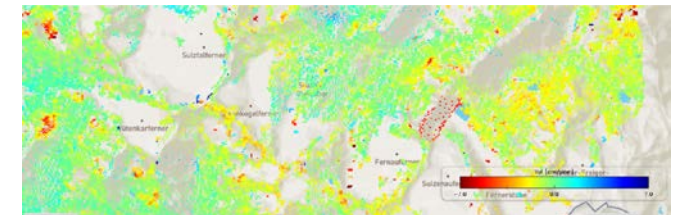
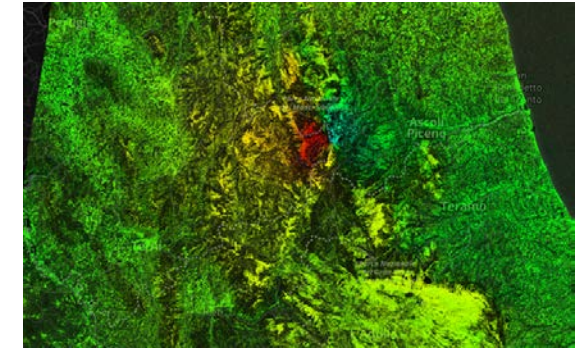




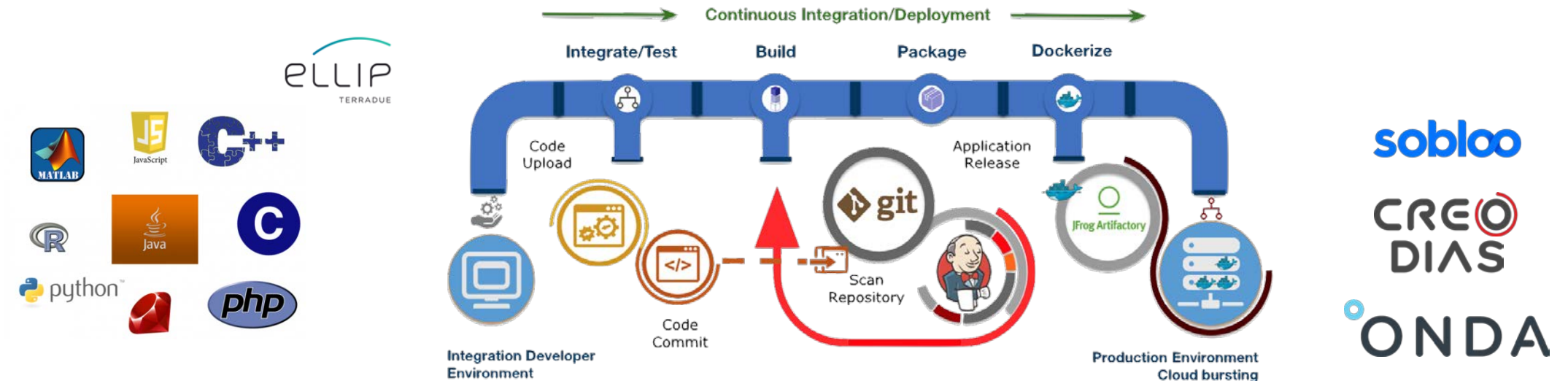
Want to apply as early adopter of the GEP Early Adopters Programme ?

contact@geohazards-tep.eu

- 25+ on-demand services using Optical & SAR data grouped in Thematic Apps, according to the defined goals of Community Managers
- New basic services providing full resolution and change detection imagery for rapid online visualization
- 8 systematic services delivering continuously updated information layers on GEP, including the large scale production of Sentinel-1 InSAR browse images at both 100m and 50m resolution over tectonic regions and volcanoes



- Applications developed in any programming language supported
 - C/C++, Java, Python, Matlab and IDL
- Continuous Integration and Deployment Environment with automatic packaging and deployment in production environments



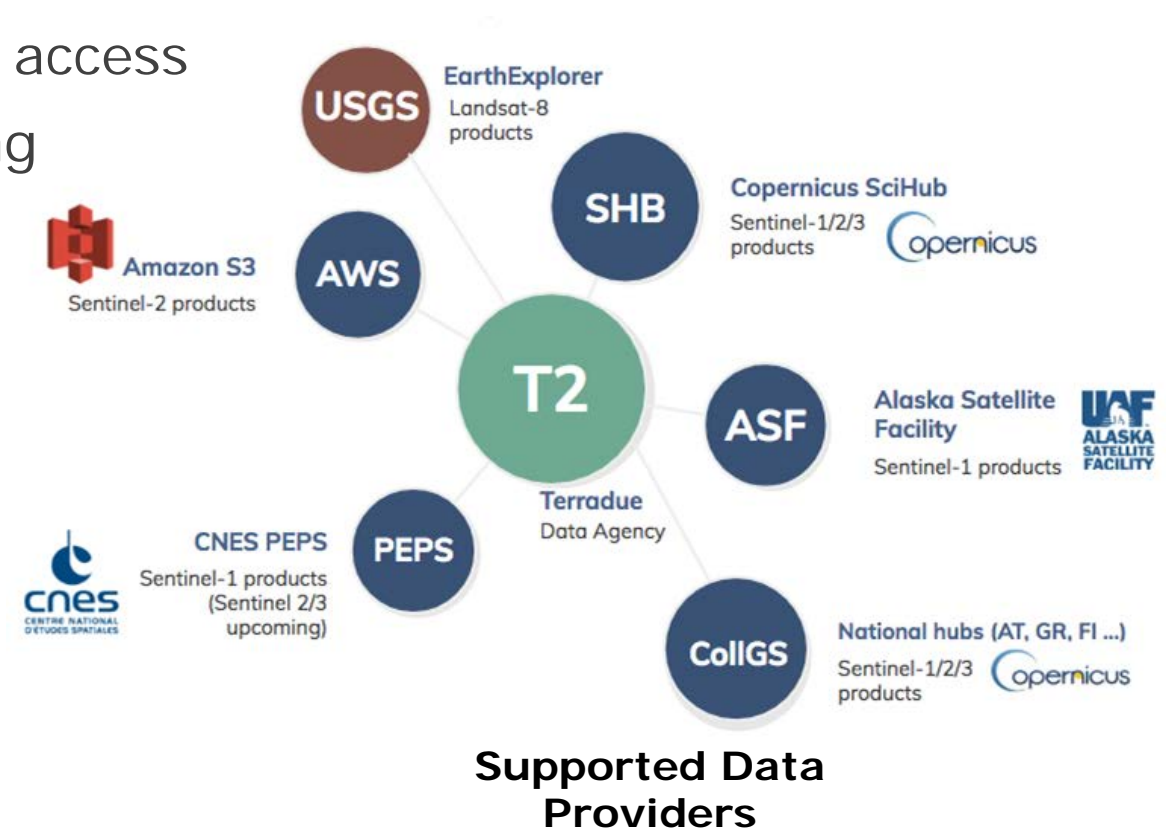
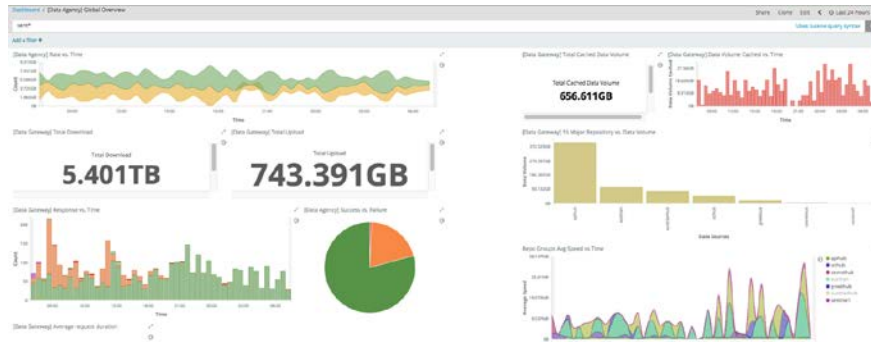
- Continuous Integration and Deployment Environment with automatic packaging & deployment in production environments
- Improved Production Center, with (auto)scalability allowing cost-effective data processing on Cloud Computing
- Deployment in multiple Cloud-based processing environments with no lock-in on a Cloud provider



Enhanced Data Gateway using OpenSearch

- Automatic multi-sourcing to optimise data access
- Programmable and systematic data caching
- Data usage accounting
- Personal cloud storage (repository)

Daily figures



ESA asked us to provide a feedback:

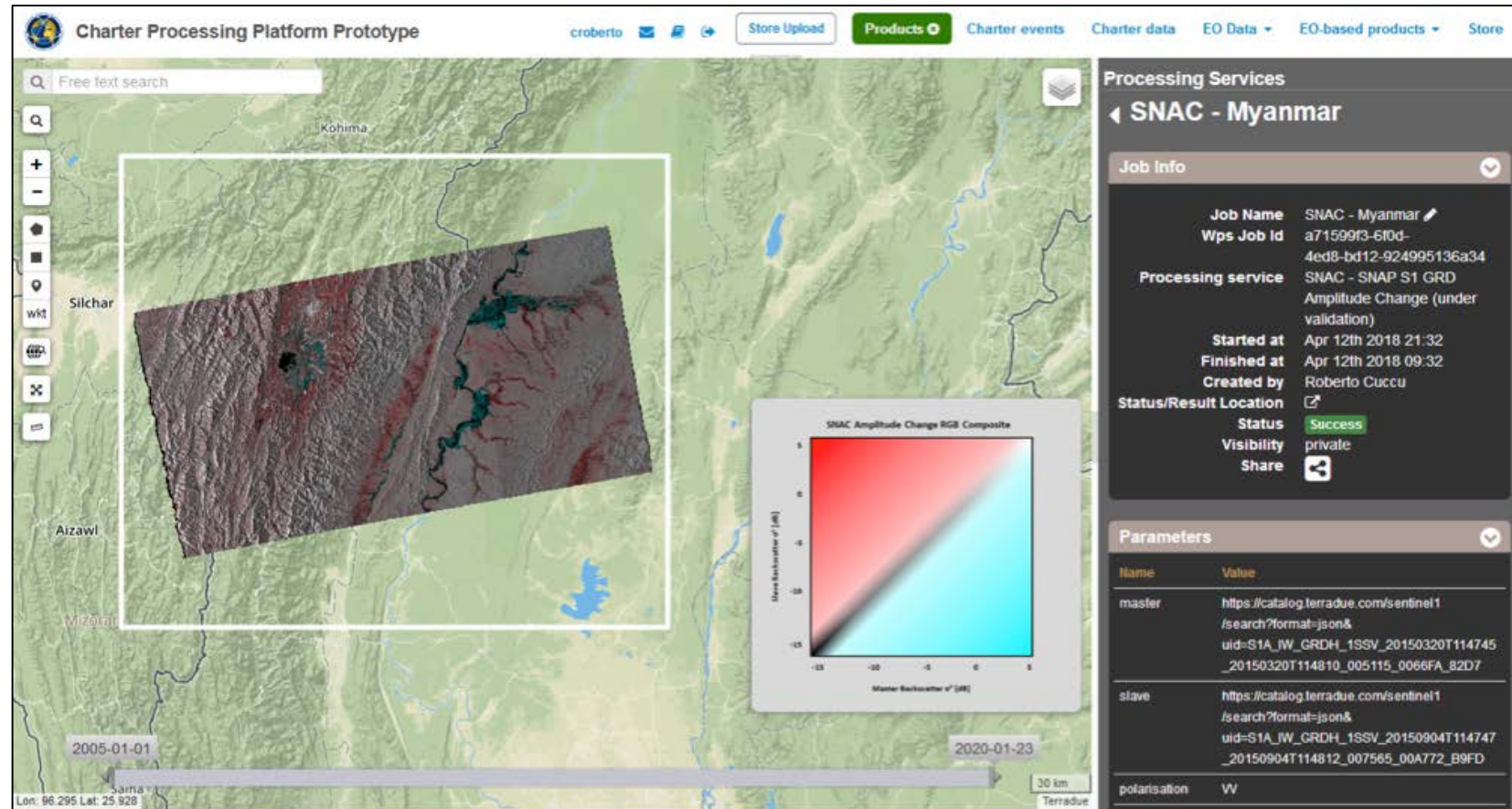
1. In what context are you using SNAP, which parts and to do what?
2. What other software do you use along with SNAP? Do they have to interact with each other?
3. What works and what doesn't?
4. What performances do you get (time, quality)?
5. What extra SNAP feature would help your work?
6. Did SNAP help you achieve everything that you expect it to?

Some examples of SNAP services

- SNAC
- COIN
- COMBI
- Active fire detection with Sentinel-3
- Burned area assessment with Sentinel-2
- CSK interferogram generation

SNAC generates RGB composite of backscattering from a pair Sentinel-1 GRD IW and EW products (e.g. pre- and post-event)

https://terradue.github.io/doc-tep-geohazards/tutorials/rss_snap_s1_snac.html



COIN produces geocoded composites of coherence and amplitude images from a pair of Sentinel-1 TOPSAR IW data pairs.

https://terradye.github.io/doc-tep-geohazards/tutorials/rss_snap_s1_coin.html

The screenshot displays the geohazards web application interface. A map of Italy is shown with a COIN product overlay. A metadata popup is visible, providing details about the product. A color scale legend for coherence is also shown. The interface includes search bars, navigation tools, and a results panel on the right.

Metadata:

Property	Value
Description	Coherence and Intensity RGB composite
Polarisation	VV
Title	coh_sigmaAvg_IW_VV_04Jun2016_28Jun2016_Coh_Ampl
Snap Version	5.0
Service Name	COIN
Processing Time	Fri Apr 6 07:48:34 UTC 2018

Color Scale Legend:

Coherence and Intensity RGB composite

Coherence

of Backscatter Average (dB)

1.0

0.75

0.5

0.25

0

0

10

20

30

40

50

60

70

80

90

100

110

120

130

140

150

160

170

180

190

200

210

220

230

240

250

260

270

280

290

300

310

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330

340

350

360

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980

990

1000

RGB band combination from single or multiple EO data product user-defined band combinations from multi-mission Optical and SAR data.

Missions: ALOS, ALOS-2, Kanopus-V, KOMPSAT-2, KOMPSAT-3, KOMPSAT-5, GF2, Landsat 8, Pleiades 1A/1B, RADARSAT-2, RapidEye, Resurs-P, Sentinel-1, Sentinel-2, SPOT 6, SPOT 7, TerraSAR-X, VRSS1 and UK-DMC 2.

<https://terradue.github.io/doc-tep->

The screenshot displays the Charter Processing Platform Prototype interface. A map shows a processed RGB band combination of satellite data. A metadata panel is open over the map, displaying the following information:

- RGB.tif**
- RGB combination**
- Blue_Product** S2A_MSIL1C_20170430T103021_N0205_R108_T...
- Blue_Product_Band** B2
- Description** RGB combination
- Green_Product** S2A_MSIL1C_20170430T103021_N0205_R108_T...
- Green_Product_Band** B3
- Red_Product** S2A_MSIL1C_20170430T103021_N0205_R108_T...
- Red_Product_Band** B8
- Service Name** Band combination
- pixelSpacingMeters** 10
- processingTime** Tue Jan 9 15:57:42 CET 2018
- Published** Jan 9th 2018
- Download** (button)
- Included search** (button)

The right sidebar shows a metadata table with the following data:

redBandIndex	band_8
greenBandProduct	https://catalog.terradue.com/sentinel2/search?format=json&uid=S2A_MSIL1C_20170430T103021_N0205_R108_T32_TMR_20170430T103024
greenBandIndex	band_3
blueBandProduct	https://catalog.terradue.com/sentinel2/search?format=json&uid=S2A_MSIL1C_20170430T103021_N0205_R108_T32_TMR_20170430T103024
blueBandIndex	band_2
targetResProduct	https://catalog.terradue.com/sentinel2/search?format=json&uid=S2A_MSIL1C_20170430T103021_N0205_R108_T32_TMR_20170430T103024
performCropping	true
SubsetBoundingB	8 177 45 278 8 455 45 399
OK	

A success message is displayed: "Success The job was completed successfully." The bottom right corner shows a "Results" section with "Found layers in the result." and a "Show results" button.

Uses Sentinel-3 SLSTR to detect hot spots to generate a product including:

- A geojson with the hotspots
- A RGB composite for descending acquisitions
- A cloud mask
- CCI Land Cover

The screenshot shows the TERRAUE web interface. The main map displays a satellite view of Portugal with a red hot spot in the Coimbra region. The interface includes a search bar, a list of search results, and a right-hand panel with parameters and a success message.

Parameters

Name	Value
source	https://tilling.terraue.com/sentinel3/search?format=geojson&SLSTR_S1_TNR_20170618T104548_20170618T104548_20170618T104548_20170618T104548_LRT_TNR_003
aoi	POLYGON ((7.36, -7.41, -10.41, -10.36, -7.36))
T1_SL_Ray_TN	320 method
SLSTR_Ray_TN	18 method
T1_SL_Ray_TN	310 method
SLSTR_Ray_TN	18 method

Success
The job was completed successfully.

Results
Found layers in the result. [Show results](#)

XML Result [Show results](#)

Technical Support [Show results](#)

Sentinel-2 burned area assessment including:

- RGB composite B12, B11, B8A
- dNBR delta normalized burn ratio
- RBR Relativized Burn Ratio

Charter Processing Platform Prototype

Upload Data Products Charter events Charter data EO Data EO-based products Community Private

Free text search

2005-01-01 2020-01-23

Lon: 128.588 Lat: 38.213

Current search result

Discovery feed for local data Total results 5

- Burned area analysis (2019-04-03T02:16:51.0240000Z/2019-04-08T02:16:09.0240000Z)
- NIR/SWIR RGB composite (2019-04-03T02:16:51.0240000Z/2019-04-03T02:16:51.0240000Z)
- NIR/SWIR RGB composite (2019-04-08T02:16:09.0240000Z/2019-04-08T02:16:09.0240000Z)
- Reproducibility-notebook-used-for-generating-dNBR-and-RBR
- Reproducibility-stage-in-notebook-for-Sentinel-2-data-for-generating-dNBR-and-RBR

Features Basket Data Packages

No results found.

Total results 0 | se.lall | inv.sel. | Remove all | Save

Created by Fabrice Brito

Status/Result Location Status Success Visibility private Share

Parameters

Name	Value
source	https://catalog.terraue.com/sentinel2/search?uid=S2A_MSIL2A_20190403T021651_N0211_R003_T52SDH_20190404T105016,https://catalog.terraue.com/sentinel2/search?uid=S2B_MSIL2A_20190408T021609_N0211_R003_T52SDH_20190408T045111
aol	POLYGON ((128.5680275793651 38.26, 128.61 38.26, 128.61 38.2, 128.5942576964478 38.2, 128.6102 38.1604, 128.4275 38.1604, 128.418 38.2536, 128.4164 38.2971, 128.4259 38.2995, 128.5369 38.3037, 128.5680275793651 38.26))

Resubmit Job

Success
The job was completed successfully.

Results

Found layers in the result. Show results

XML Result

Technical Support

COSMO-SkyMed Differential SAR Interferometry using SNAP.

This service performs an InSAR workflow on a pair (master, slave) of COSMO-SkyMed single look complex (L1A SCS) acquisitions producing interferograms and coherence map

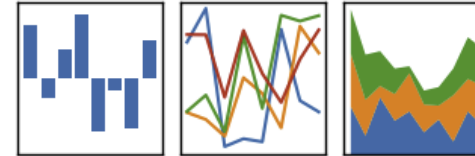
The screenshot shows the TerraUE web interface. At the top, there's a search bar with 'Free text search' and a 'geohazards tep' dropdown. The main map area displays a satellite view of Pokhara, Nepal, with a white box highlighting a specific area. The map includes labels for various locations like Borang, Syabru Beni, Langtang National Park, Anbu Khaireni, Shiva Puri Conservation Area, Chautara, Bharatpur, mandu atan, Godawari forest, Bhimeshwar, Royal Chitwan National Park, and Ramechhan. A timeline at the bottom of the map shows dates from 2000-03-12 to 2030-03-12. Below the map, there's a 'Discovery feed for local data' section with 4 results, including 'Reproducibility notebook used for generating CSK_IFG...', 'Reproducibility-stage-in-notebook-for-CSK-data-for-generating-CSK_IFG...', 'SNAP InSAR CSK - Interferometric coherence...', and 'SNAP InSAR CSK - Interferometric phase...'. To the right, there's a sidebar with metadata and parameters.

Name	Value
Name	SNAP CSK DInSAR v0.9
Id	15638c4f-e199-45a1-8360-355d5c1828ca
Processing service	SNAP CSK DInSAR
Service version	0.9
Started at	Sep 5th 2019 12:59
Finished at	Sep 5th 2019 14:06
Created by	fpacini
Status/Result Location	📄
Status	Success
Visibility	private
Share	🔗

Name	Value
1 - source	https://recast.terraue.com/t2api/search/fpacini/results?uid=D8FA0DF117ADF730567A0B935AFAA3C741373911
2 - source	https://recast.terraue.com/t2api/search/fpacini/results?uid=410EB30D59868427D24FBD41F3C153D0545263C7
aol	POLYGON((84.905 27.652,84.905 27.917,85.232 27.917,85.232 27.652,84.905 27.652))
fft_size	32

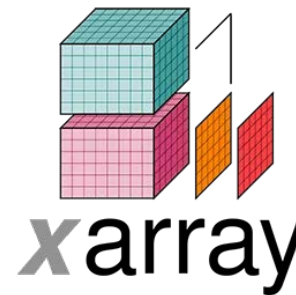
- Libraries and toolboxes:

- Orfeo Toolbox
- Gdal
- pandas/geopandas
- NumPy



- Environments

- Jupyter
- Xarray
- Dask



- Processing

- YARN, OOZIE
- Kubernetes



The importance of Snappy

"I CERTAINLY didn't set out to create a language that was intended for mass consumption," says **Guido van Rossum**, a Dutch computer scientist who devised **Python**, a programming language, in 1989.

But nearly three decades on, his invention has overtaken almost all of its rivals and brought coding to the fingertips of people who were once baffled by it.



Using Snappy in notebooks to plot and analyse Sentinel data

```
In [5]: import numpy as np
import matplotlib
import matplotlib.pyplot as plt
import matplotlib.colors as colors

%matplotlib inline

def plotBand(product, band, vmin, vmax):
    band = product.getBand(band)
    w = band.getRasterWidth()
    h = band.getRasterHeight()

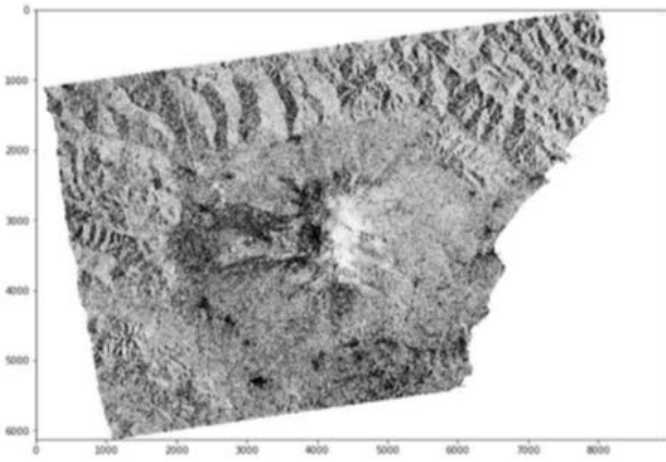
    band_data = np.zeros(w * h, np.float32)
    band.readPixels(0, 0, w, h, band_data)
    band_data.shape = h, w

    width = 12
    height = 12
    plt.figure(figsize=(width, height))
    imgplot = plt.imshow(band_data, cmap=plt.cm.binary, vmin=vmin, vmax=vmax)

    return imgplot

plotBand(terrain, 'Sigma0_' + polarization, 0, 0.3)

Out[5]: <matplotlib.image.AxesImage at 0x7f6e2370e990>
```



• Step 4: Plot an RGB image

```
In [6]: red_radiance = reproject.getBand('Oa08_radiance')
green_radiance = reproject.getBand('Oa05_radiance')
blue_radiance = reproject.getBand('Oa04_radiance')

w = red_radiance.getRasterWidth()
h = red_radiance.getRasterHeight()

red_radiance_data = np.zeros(w * h, np.float32)
red_radiance.readPixels(0, 0, w, h, red_radiance_data)
red_radiance_data.shape = h, w

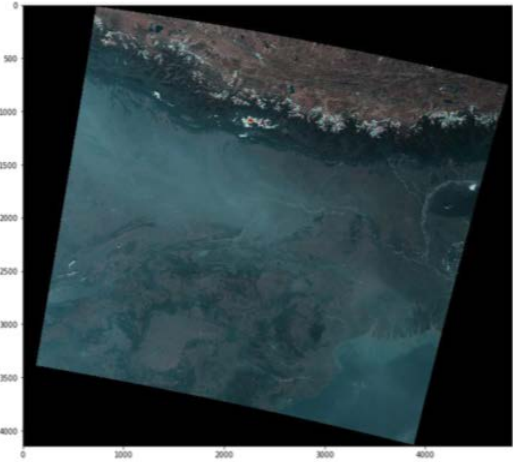
green_radiance_data = np.zeros(w * h, np.float32)
green_radiance.readPixels(0, 0, w, h, green_radiance_data)
green_radiance_data.shape = h, w

blue_radiance_data = np.zeros(w * h, np.float32)
blue_radiance.readPixels(0, 0, w, h, blue_radiance_data)
blue_radiance_data.shape = h, w

xmax=200
red = (red_radiance_data*256/(xmax-np.amin(red_radiance_data)))
green = (green_radiance_data*256/(xmax-np.amin(green_radiance_data)))
blue = (blue_radiance_data*256/(xmax-np.amin(blue_radiance_data)))

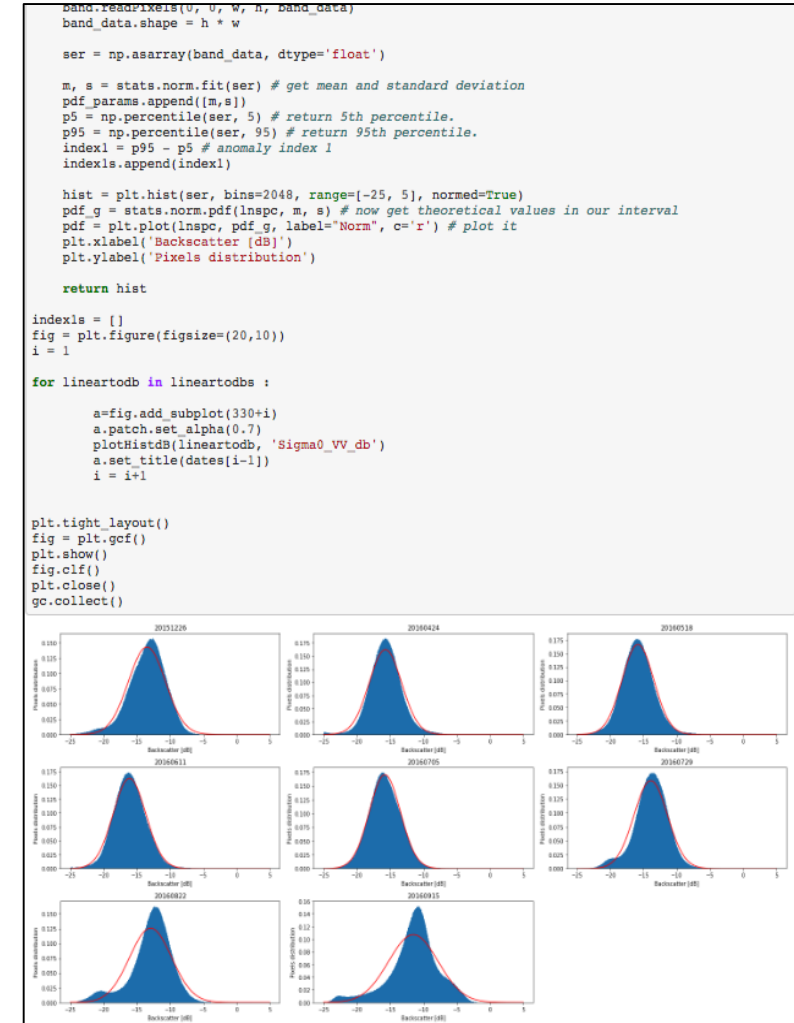
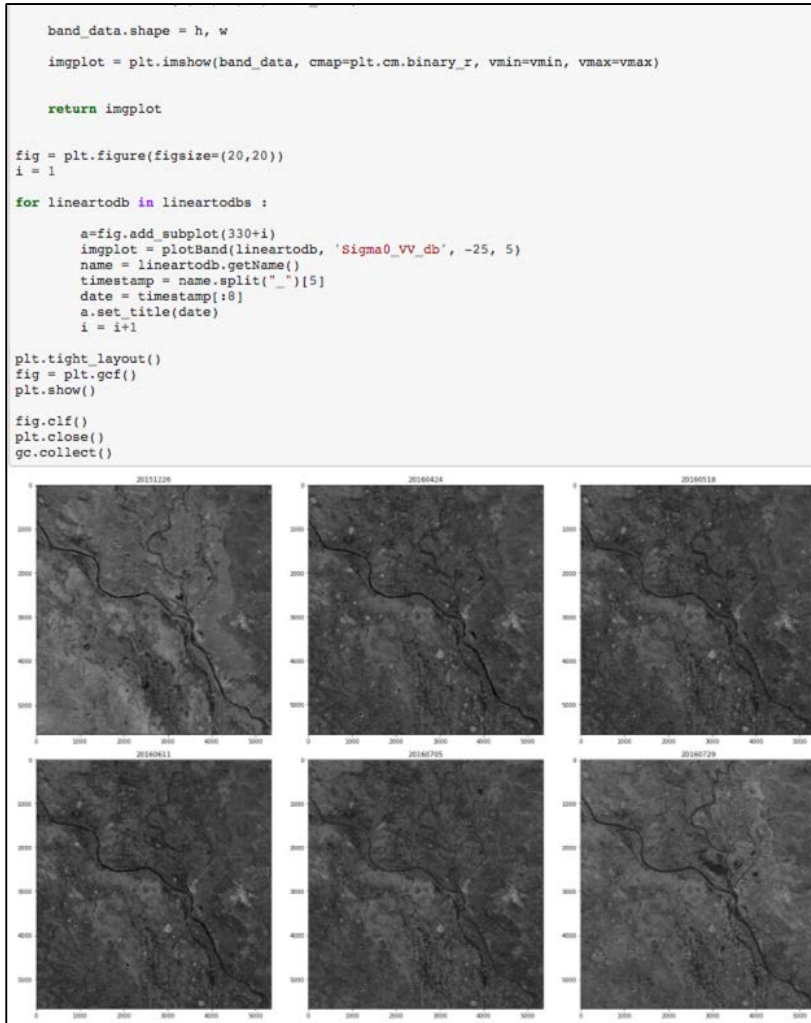
rgb_uint8 = np.dstack((red, green, blue)).astype(np.uint8)

width = 12
height = 12
plt.figure(figsize=(width, height))
img = Image.fromarray(rgb_uint8)
imgplot = plt.imshow(img)
```



Using Snappy to analyse a stack of GRD Sentinel-1 data

Backscatter profiles for reference image used in flood change detection analysis



What doesn't work: Snappy

Snappy is slow compared to GPT

Snappy has memory issues,
results with Snappy are not the
same as with GPT

Conclusion:

Snappy is barely used in our
services, maybe just for
inspecting band names for
example. Sad.

A

Slower **snappy** processing

■ development ■ python

Jul '17 - I have come back to use **snappy** after some time, and I am seeing a slower processing of the **snappy** module when writing a product in a numpy array (10390x10390 pixels) , and also whe...

C

Snappy very slow

■ s2tbx

Jan '17 - Hello, I'm trying to calculate the NDVI using the snappy_ndvi.py example but the processing is extremely **slow**, maybe more than one day to process 30978 lines. However, the time employed when I use the dest...

T

Snappy - So slowly to calculate NDVI with Mask

■ development ■ python

Nov '17 - Hi, I try to use the **snappy** to calculate NDVI with mask, but the programme is very **slow**. But when I used the SNAP Desktop it's quickly. The Product is S2A -level, 10980*10980, m...

A

Snappy running really slow

■ development ■ python

May 13 - I'm trying to run the following operations in **snappy**: Calibration > Speckle-Filter > Terrain-Correction in **Snappy**, but it is taking way too long. In the SNAP application it takes about 45 secs to proces...

What doesn't work: Snappy

```
10 class GraphProcessor():
11
12     def __init__(self, wdir='.'):
13         self.root = etree.Element('graph')
14
15         version = etree.SubElement(self.root, 'version')
16         version.text = '1.0'
17         self.pid = None
18         self.p = None
19         self.wdir = wdir
20
21     def view_graph(self):
22
23         print(etree.tostring(self.root , pretty_print=True))
24
25     def add_node(self, node_id, operator, parameters, source):
26
27         xpath_expr = '/graph/node[@id="%s"]' % node_id
28
29         if len(self.root.xpath(xpath_expr)) != 0:
30
31             node_elem = self.root.xpath(xpath_expr)[0]
32             operator_elem = self.root.xpath(xpath_expr + '/operator')[0]
33             sources_elem = self.root.xpath(xpath_expr + '/sources')[0]
34             parameters_elem = self.root.xpath(xpath_expr + '/parameters')
35
36             for key, value in parameters.iteritems():
37
38                 if key == 'targetBandDescriptors':
39
40                     parameters_elem.append(etree.fromstring(value))
41
42             else:
43                 p_elem = self.root.xpath(xpath_expr + '/parameters/%s' % key)[0]
44
45                 if value is not None:
46                     if value[0] != '<':
47                         p_elem.text = value
48                     else:
49                         p_elem.text.append(etree.fromstring(value))
```

```
122     def run(self):
123
124         os.environ['LD_LIBRARY_PATH'] = '.'
125
126         print('Processing the graph')
127
128         fd, path = tempfile.mkstemp()
129
130         try:
131
132             self.save_graph(filename=path)
133             options = ['/opt/snap/bin/gpt',
134                       '-x',
135                       '-c',
136                       '2048M',
137                       path]
138
139             p = subprocess.Popen(options,
140                                 stdout=subprocess.PIPE, stdin=subprocess.PIPE, stderr=subprocess.PIPE)
141
142             print('Process PID: %s' % p.pid)
143             res, err = p.communicate()
144             print(res, err)
145         finally:
146             os.remove(path)
147
148         print('Done.')
```

We all had to write code to generate the graph XML and do a system call to /opt/snap/bin/gpt

What doesn't work: Snappy

```
def burned_area(**kwargs):  
  
    options = dict()  
  
    operators = ['Read',  
                'BandMaths',  
                'Write']  
  
    for operator in operators:  
  
        print 'Getting default values for Operator {}'.format(operator)  
        parameters = get_operator_default_parameters(operator)  
  
        options[operator] = parameters  
  
    for key, value in kwargs.items():  
  
        print 'Updating Operator {}'.format(key)  
        options[key.replace('_', '-')].update(value)  
  
    mygraph = GraphProcessor()  
  
    for index, operator in enumerate(operators):  
  
        print 'Adding Operator {} to graph'.format(operator)  
        if index == 0:  
            source_node_id = ''  
  
        else:  
            source_node_id = operators[index - 1]  
  
        mygraph.add_node(operator,  
                        operator,  
                        options[operator], source_node_id)  
  
    mygraph.view_graph()  
  
    mygraph.run()
```

```
for index_swath, swath in enumerate(swaths):  
    print 'process swath {}'.format(swath)  
  
    # Read  
    operator = 'Read'  
  
    source_node_id = ''  
  
    node_id = 'Read'  
  
    parameters = get_operator_default_parameters(operator)  
    print products[products.date == date].local_path.values[0]  
    parameters['file'] = products[products.date == date].local_path.values[0]  
  
    mygraph.add_node(node_id, operator, parameters, source_node_id)  
  
    # TOPSAR-Split  
    operator = 'TOPSAR-Split'  
  
    source_node_id = node_id  
  
    node_id = 'TOPSAR-Split'  
  
    parameters = get_operator_default_parameters(operator)  
    parameters['subswath'] = swath  
    parameters['selectedPolarisations'] = 'VV'  
  
    mygraph.add_node(node_id, operator, parameters, source_node_id)  
  
    # Apply-Orbit-File  
    operator = 'Apply-Orbit-File'  
  
    source_node_id = node_id  
  
    node_id = 'Apply-Orbit-File'  
  
    parameters = get_operator_default_parameters(operator)  
    parameters['orbitType'] = 'Sentinel Precise (Auto Download)'  
  
    mygraph.add_node(node_id, operator, parameters, source_node_id)
```

Examples of such “wrapping code”

SNAP provides an excellent framework to develop additional processors

What is great: gpt processor

SNAP / ... / SNAP Engine extension development

How to integrate a new processor



Created by Nicolas Ducoin
Last updated 2016-05-27 by Luis Veci

Processors in SNAP are implemented via Graph Processing Framework (GPF) Operators. An Operator consists of the block of code that will manipulate a data product and create a new data product as a result. The operator will be used within the graph processing framework.

A new Operator can be created by extending the base Operator class and implementing the Operator interface. An Operator basically takes a source product as input and creates a new target product within `initialize()`.

The algorithm implementation for what your operator does will go inside **`computeTile()`** or **`computeTiles()`**.

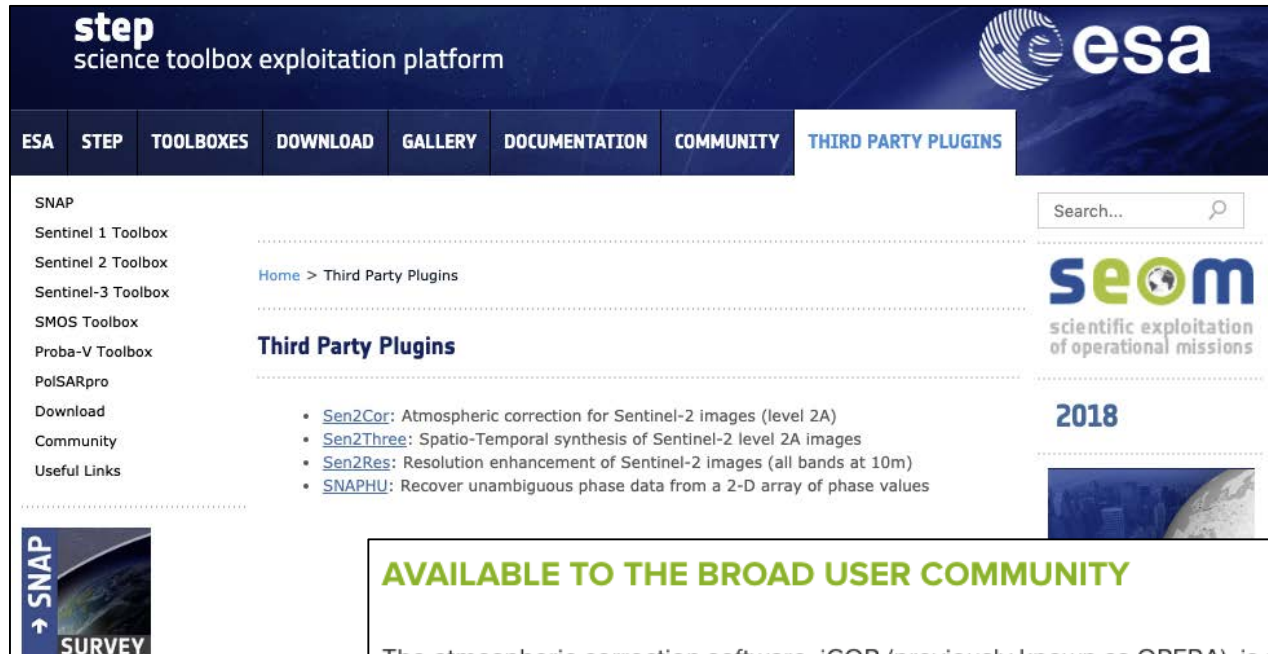
```
public interface Operator {
    OperatorSpi getSpi();
    Product initialize(OperatorContext context);
    void computeTile(Tile targetTile, ProgressMonitor pm);
    void computeTileStack(Rectangle targetTileRectangle, ProgressMonitor pm);
    void dispose();
}
```

What doesn't work: plugins

On the other hand, we see no value in providing plugins.

In this case, SNAP acts as a wrapper on top of CLI applications.

We go straight to the CLI.



The screenshot shows the 'step science toolbox exploitation platform' website. The navigation menu includes 'ESA', 'STEP', 'TOOLBOXES', 'DOWNLOAD', 'GALLERY', 'DOCUMENTATION', 'COMMUNITY', and 'THIRD PARTY PLUGINS'. The 'THIRD PARTY PLUGINS' section is active, displaying a list of plugins: SNAP, Sentinel 1 Toolbox, Sentinel 2 Toolbox, Sentinel-3 Toolbox, SMOS Toolbox, Proba-V Toolbox, PolSARpro, Download, Community, and Useful Links. A search bar is visible in the top right corner. The 'Third Party Plugins' section lists several plugins, including [Sen2Cor](#), [Sen2Three](#), [Sen2Res](#), and [SNAPHU](#). A sidebar on the right features the 'seom' logo and the text 'scientific exploitation of operational missions'.

AVAILABLE TO THE BROAD USER COMMUNITY

The atmospheric correction software, iCOR (previously known as OPERA), is now available to the broad user community through the ESA Sentinel Application Platform (SNAP) for the **atmospheric correction of Sentinel-2 and Landsat-8 data**.

By implementing iCOR in SNAP, **researchers can test iCOR for their own study areas and experiment** with the different functionalities the new tool has to offer. The iCOR SNAP plug-in can be **freely downloaded**.



Performances


- Processing performance are OK for us
- SNAP Graph developer learning curve could be better: several GOTCHAS here and there (e.g. Thermal Noise Removal)
- Split Graphs is a mandatory strategy

Extra SNAP feature would help

- Cloud Optimized Geotiff as an output format
- BEAM-DIMAP as an internal format
- 'no data' support

Does SNAP help you achieve everything that you expect it to?

- A single toolbox will never be able to gather all features and functions we need to build services
- We are used to cherry picking what works from toolboxes and libraries and avoid what doesn't

A photograph of a space station in orbit over Earth. The station's structure, including a large gold-colored cylindrical module and various mechanical components, is visible in the upper right corner. The Earth's surface below is covered in a dense layer of white clouds, with some darker landmasses visible. The horizon of the planet is a thin blue line against the blackness of space.

TERRA)UE

Advancing Earth Science

Thank you !